

W1: Dallas' 1-wire bus

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by David Fries

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Table of Contents

| | |
|----------------------------------------|----|
| 1. W1 API internal to the kernel | 1 |
| W1 API internal to the kernel | 1 |
| drivers/w1/w1.h | 1 |
| drivers/w1/w1.c | 8 |
| drivers/w1/w1_family.h | 10 |
| drivers/w1/w1_family.c | 12 |
| drivers/w1/w1_int.c | 14 |
| drivers/w1/w1_netlink.h | 16 |
| drivers/w1/w1_io.c | 21 |

Chapter 1. W1 API internal to the kernel

W1 API internal to the kernel

drivers/w1/w1.h

W1 core functions.

Name

struct w1_reg_num — broken out slave device id

Synopsis

```
struct w1_reg_num {
#ifdef __LITTLE_ENDIAN_BITFIELD
    __u64 family:8;
    __u64 id:48;
    __u64 crc:8;
#elif defined(__BIG_ENDIAN_BITFIELD)
    __u64 crc:8;
    __u64 id:48;
    __u64 family:8;
#else
#error "Please fix <asm/byteorder.h>"
#endif
};
```

Members

| | |
|--------|-------------------------------------------|
| family | identifies the type of device |
| id | along with family is the unique device id |
| crc | checksum of the other bytes |
| crc | checksum of the other bytes |
| id | along with family is the unique device id |
| family | identifies the type of device |

Name

struct w1_slave — holds a single slave device on the bus

Synopsis

```
struct w1_slave {
    struct module * owner;
    unsigned char name[W1_MAXNAMELEN];
    struct list_head w1_slave_entry;
    struct w1_reg_num reg_num;
    atomic_t refcnt;
    int ttl;
    unsigned long flags;
    struct w1_master * master;
    struct w1_family * family;
    void * family_data;
    struct device dev;
};
```

Members

| | |
|---------------------|----------------------------------------------------------|
| owner | Points to the one wire “wire” kernel module. |
| name[W1_MAXNAMELEN] | Device id is ascii. |
| w1_slave_entry | data for the linked list |
| reg_num | the slave id in binary |
| refcnt | reference count, delete when 0 |
| ttl | decrement per search this slave isn't found, deatch at 0 |
| flags | bit flags for W1_SLAVE_ACTIVE W1_SLAVE_DETACH |
| master | bus which this slave is on |
| family | module for device family type |
| family_data | pointer for use by the family module |
| dev | kernel device identifier |

Name

struct w1_bus_master — operations available on a bus master

Synopsis

```
struct w1_bus_master {
    void * data;
    u8 (* read_bit) (void *);
    void (* write_bit) (void *, u8);
    u8 (* touch_bit) (void *, u8);
    u8 (* read_byte) (void *);
    void (* write_byte) (void *, u8);
    u8 (* read_block) (void *, u8 *, int);
    void (* write_block) (void *, const u8 *, int);
    u8 (* triplet) (void *, u8);
    u8 (* reset_bus) (void *);
    u8 (* set_pullup) (void *, int);
    void (* search) (void *, struct w1_master *, u8, w1_slave_found_callback);
};
```

Members

| | |
|-------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| data | the first parameter in all the functions below |
| read_bit | Sample the line level <i>return</i> the level read (0 or 1) |
| write_bit | Sets the line level |
| touch_bit | the lowest-level function for devices that really support the 1-wire protocol. touch_bit(0) = write-0 cycle touch_bit(1) = write-1 / read cycle <i>return</i> the bit read (0 or 1) |
| read_byte | Reads a bytes. Same as 8 touch_bit(1) calls. <i>return</i> the byte read |
| write_byte | Writes a byte. Same as 8 touch_bit(x) calls. |
| read_block | Same as a series of read_byte calls <i>return</i> the number of bytes read |
| write_block | Same as a series of write_byte calls |
| triplet | Combines two reads and a smart write for ROM searches <i>return</i> bit0=Id bit1=comp_id bit2=dir_taken |
| reset_bus | long write-0 with a read for the presence pulse detection <i>return</i> -1=Error, 0=Device present, 1=No device present |
| set_pullup | Put out a strong pull-up pulse of the specified duration. <i>return</i> -1=Error, 0=completed |
| search | Really nice hardware can handles the different types of ROM search w1_master* is passed to the slave found callback. u8 is search_type, W1_SEARCH or W1_ALARM_SEARCH |

Note

read_bit and write_bit are very low level functions and should only be used with hardware that doesn't really support 1-wire operations, like a parallel/serial port. Either define read_bit and write_bit OR define, at minimum, touch_bit and reset_bus.

Name

enum w1_master_flags — bitfields used in w1_master.flags

Synopsis

```
enum w1_master_flags {  
    W1_ABORT_SEARCH,  
    W1_WARN_MAX_COUNT  
};
```

Constants

W1_ABORT_SEARCH abort searching early on shutdown

W1_WARN_MAX_COUNT emit warning when the maximum count is reached

Name

struct w1_master — one per bus master

Synopsis

```
struct w1_master {
    struct list_head w1_master_entry;
    struct module * owner;
    unsigned char name[W1_MAXNAMELEN];
    struct mutex list_mutex;
    struct list_head slist;
    struct list_head async_list;
    int max_slave_count;
    int slave_count;
    unsigned long attempts;
    int slave_ttl;
    int initialized;
    u32 id;
    int search_count;
    u64 search_id;
    atomic_t refcnt;
    void * priv;
    int enable_pullup;
    int pullup_duration;
    long flags;
    struct task_struct * thread;
    struct mutex mutex;
    struct mutex bus_mutex;
    struct device_driver * driver;
    struct device dev;
    struct w1_bus_master * bus_master;
    u32 seq;
};
```

Members

| | |
|---------------------|--------------------------------------------------|
| w1_master_entry | master linked list |
| owner | module owner |
| name[W1_MAXNAMELEN] | dynamically allocate bus name |
| list_mutex | protect slist and async_list |
| slist | linked list of slaves |
| async_list | linked list of netlink commands to execute |
| max_slave_count | maximum number of slaves to search for at a time |
| slave_count | current number of slaves known |
| attempts | number of searches ran |

| | |
|-----------------|---------------------------------------------------|
| slave_ttl | number of searches before a slave is timed out |
| initialized | prevent init/removal race conditions |
| id | w1 bus number |
| search_count | number of automatic searches to run, -1 unlimited |
| search_id | allows continuing a search |
| refcnt | reference count |
| priv | private data storage |
| enable_pullup | allows a strong pullup |
| pullup_duration | time for the next strong pullup |
| flags | one of w1_master_flags |
| thread | thread for bus search and netlink commands |
| mutex | protect most of w1_master |
| bus_mutex | protect concurrent bus access |
| driver | sysfs driver |
| dev | sysfs device |
| bus_master | io operations available |
| seq | sequence number used for netlink broadcasts |

Name

struct w1_async_cmd — execute callback from the w1_process kthread

Synopsis

```
struct w1_async_cmd {
    struct list_head async_entry;
    void (* cb) (struct w1_master *dev, struct w1_async_cmd *async_cmd);
};
```

Members

| | |
|-------------|-------------------------------------------------------------------------|
| async_entry | link entry |
| cb | callback function, must list_del and destroy this list before returning |

Description

When inserted into the w1_master async_list, w1_process will execute the callback. Embed this into the structure with the command details.

drivers/w1/w1.c

W1 core functions.

Name

`w1_search` — Performs a ROM Search & registers any devices found.

Synopsis

```
void    w1_search    (struct    w1_master    *    dev,    u8    search_type,  
w1_slave_found_callback cb);
```

Arguments

| | |
|--------------------|-------------------------------------------------------------------------------------------------|
| <i>dev</i> | The master device to search |
| <i>search_type</i> | W1_SEARCH to search all devices, or W1_ALARM_SEARCH to return only devices in the alarmed state |
| <i>cb</i> | Function to call when a device is found |

Description

The 1-wire search is a simple binary tree search. For each bit of the address, we read two bits and write one bit. The bit written will put to sleep all devies that don't match that bit. When the two reads differ, the direction choice is obvious. When both bits are 0, we must choose a path to take. When we can scan all 64 bits without having to choose a path, we are done.

See “Application note 187 1-wire search algorithm” at www.maxim-ic.com

Name

`w1_process_callbacks` — execute each `dev->async_list` callback entry

Synopsis

```
int w1_process_callbacks (struct w1_master * dev);
```

Arguments

dev w1_master device

Description

The w1 master `list_mutex` must be held.

Return

1 if there were commands to executed 0 otherwise

`drivers/w1/w1_family.h`

Allows registering device family operations.

Name

struct w1_family_ops — operations for a family type

Synopsis

```
struct w1_family_ops {  
    int (* add_slave) (struct w1_slave *);  
    void (* remove_slave) (struct w1_slave *);  
    const struct attribute_group ** groups;  
};
```

Members

| | |
|--------------|--------------|
| add_slave | add_slave |
| remove_slave | remove_slave |
| groups | sysfs group |

Name

struct w1_family — reference counted family structure.

Synopsis

```
struct w1_family {
    struct list_head family_entry;
    u8 fid;
    struct w1_family_ops * fops;
    atomic_t refcnt;
};
```

Members

| | |
|--------------|----------------------------|
| family_entry | family linked list |
| fid | 8 bit family identifier |
| fops | operations for this family |
| refcnt | reference counter |

drivers/w1/w1_family.c

Allows registering device family operations.

Name

`wl_register_family` — register a device family driver

Synopsis

```
int wl_register_family (struct wl_family * newf);
```

Arguments

newf family to register

Name

`w1_unregister_family` — unregister a device family driver

Synopsis

```
void w1_unregister_family (struct w1_family * fent);
```

Arguments

fent family to unregister

drivers/w1/w1_int.c

W1 internal initialization for master devices.

Name

`w1_add_master_device` — registers a new master device

Synopsis

```
int w1_add_master_device (struct w1_bus_master * master);
```

Arguments

master master bus device to register

Name

`w1_remove_master_device` — unregister a master device

Synopsis

```
void w1_remove_master_device (struct w1_bus_master * bm);
```

Arguments

bm master bus device to remove

drivers/w1/w1_netlink.h

W1 external netlink API structures and commands.

Name

enum w1_cn_msg_flags — bitfield flags for struct cn_msg.flags

Synopsis

```
enum w1_cn_msg_flags {  
    W1_CN_BUNDLE  
};
```

Constants

W1_CN_BUNDLE Request bundling replies into fewer messages. Be prepared to handle multiple struct cn_msg, struct w1_netlink_msg, and struct w1_netlink_cmd in one packet.

Name

enum w1_netlink_message_types — message type

Synopsis

```
enum w1_netlink_message_types {  
    W1_SLAVE_ADD,  
    W1_SLAVE_REMOVE,  
    W1_MASTER_ADD,  
    W1_MASTER_REMOVE,  
    W1_MASTER_CMD,  
    W1_SLAVE_CMD,  
    W1_LIST_MASTERS  
};
```

Constants

| | |
|------------------|------------------------------------------------------------------------|
| W1_SLAVE_ADD | notification that a slave device was added |
| W1_SLAVE_REMOVE | notification that a slave device was removed |
| W1_MASTER_ADD | notification that a new bus master was added |
| W1_MASTER_REMOVE | notification that a bus master was removed |
| W1_MASTER_CMD | initiate operations on a specific master |
| W1_SLAVE_CMD | sends reset, selects the slave, then does a read/write/touch operation |
| W1_LIST_MASTERS | used to determine the bus master identifiers |

Name

struct w1_netlink_msg — holds w1 message type, id, and result

Synopsis

```
struct w1_netlink_msg {
    __u8 type;
    __u8 status;
    __u16 len;
    union id;
    __u8 data[0];
};
```

Members

| | |
|---------|-------------------------------------------------------------------|
| type | one of enum w1_netlink_message_types |
| status | kernel feedback for success 0 or errno failure value |
| len | length of data following w1_netlink_msg |
| id | union holding master bus id (msg.id) and slave device id (id[8]). |
| data[0] | start address of any following data |

Description

The base message structure for w1 messages over netlink. The netlink connector data sequence is, struct nlmsg_hdr, struct cn_msg, then one or more struct w1_netlink_msg (each with optional data).

Name

enum w1_commands — commands available for master or slave operations

Synopsis

```
enum w1_commands {  
    W1_CMD_READ,  
    W1_CMD_WRITE,  
    W1_CMD_SEARCH,  
    W1_CMD_ALARM_SEARCH,  
    W1_CMD_TOUCH,  
    W1_CMD_RESET,  
    W1_CMD_SLAVE_ADD,  
    W1_CMD_SLAVE_REMOVE,  
    W1_CMD_LIST_SLAVES,  
    W1_CMD_MAX  
};
```

Constants

| | |
|---------------------|-------------------------------------------------------------------------------------|
| W1_CMD_READ | read len bytes |
| W1_CMD_WRITE | write len bytes |
| W1_CMD_SEARCH | initiate a standard search, returns only the slave devices found during that search |
| W1_CMD_ALARM_SEARCH | search for devices that are currently alarming |
| W1_CMD_TOUCH | Touches a series of bytes. |
| W1_CMD_RESET | sends a bus reset on the given master |
| W1_CMD_SLAVE_ADD | adds a slave to the given master, 8 byte slave id at data[0] |
| W1_CMD_SLAVE_REMOVE | removes a slave to the given master, 8 byte slave id at data[0] |
| W1_CMD_LIST_SLAVES | list of slaves registered on this master |
| W1_CMD_MAX | number of available commands |

Name

struct w1_netlink_cmd — holds the command and data

Synopsis

```
struct w1_netlink_cmd {  
    __u8 cmd;  
    __u8 res;  
    __u16 len;  
    __u8 data[0];  
};
```

Members

| | |
|---------|-----------------------------------------|
| cmd | one of enum w1_commands |
| res | reserved |
| len | length of data following w1_netlink_cmd |
| data[0] | start address of any following data |

Description

One or more struct w1_netlink_cmd is placed starting at w1_netlink_msg.data each with optional data.

drivers/w1/w1_io.c

W1 input/output.

Name

`w1_write_8` — Writes 8 bits.

Synopsis

```
void w1_write_8 (struct w1_master * dev, u8 byte);
```

Arguments

dev the master device

byte the byte to write

Name

`w1_read_8` — Reads 8 bits.

Synopsis

```
u8 w1_read_8 (struct w1_master * dev);
```

Arguments

dev the master device

Return

the byte read

Name

`w1_write_block` — Writes a series of bytes.

Synopsis

```
void w1_write_block (struct w1_master * dev, const u8 * buf, int len);
```

Arguments

dev the master device

buf pointer to the data to write

len the number of bytes to write

Name

`w1_touch_block` — Touches a series of bytes.

Synopsis

```
void w1_touch_block (struct w1_master * dev, u8 * buf, int len);
```

Arguments

dev the master device

buf pointer to the data to write

len the number of bytes to write

Name

`w1_read_block` — Reads a series of bytes.

Synopsis

```
u8 w1_read_block (struct w1_master * dev, u8 * buf, int len);
```

Arguments

dev the master device

buf pointer to the buffer to fill

len the number of bytes to read

Return

the number of bytes read

Name

`w1_reset_bus` — Issues a reset bus sequence.

Synopsis

```
int w1_reset_bus (struct w1_master * dev);
```

Arguments

dev the master device

Return

0=Device present, 1=No device present or error

Name

`w1_reset_select_slave` — reset and select a slave

Synopsis

```
int w1_reset_select_slave (struct w1_slave * sl);
```

Arguments

sl the slave to select

Description

Resets the bus and then selects the slave by sending either a skip rom or a rom match. A skip rom is issued if there is only one device registered on the bus. The w1 master lock must be held.

Return

0=success, anything else=error

Name

`w1_reset_resume_command` — resume instead of another match ROM

Synopsis

```
int w1_reset_resume_command (struct w1_master * dev);
```

Arguments

dev the master device

Description

When the workflow with a slave amongst many requires several successive commands a reset between each, this function is similar to doing a reset then a match ROM for the last matched ROM. The advantage being that the matched ROM step is skipped in favor of the resume command. The slave must support the command of course.

If the bus has only one slave, traditionnaly the match ROM is skipped and a “SKIP ROM” is done for efficiency. On multi-slave busses, this doesn't work of course, but the resume command is the next best thing.

The w1 master lock must be held.

Name

`w1_next_pullup` — register for a strong pullup

Synopsis

```
void w1_next_pullup (struct w1_master * dev, int delay);
```

Arguments

dev the master device

delay time in milliseconds

Description

Put out a strong pull-up of the specified duration after the next write operation. Not all hardware supports strong pullups. Hardware that doesn't support strong pullups will sleep for the given time after the write operation without a strong pullup. This is a one shot request for the next write, specifying zero will clear a previous request. The w1 master lock must be held.

Return

0=success, anything else=error

Name

`w1_touch_bit` — Generates a write-0 or write-1 cycle and samples the level.

Synopsis

```
u8 w1_touch_bit (struct w1_master * dev, int bit);
```

Arguments

dev the master device

bit 0 - write a 0, 1 - write a 0 read the level

Name

`w1_write_bit` — Generates a write-0 or write-1 cycle.

Synopsis

```
void w1_write_bit (struct w1_master * dev, int bit);
```

Arguments

dev the master device

bit bit to write

Description

Only call if `dev->bus_master->touch_bit` is NULL

Name

w1_pre_write — pre-write operations

Synopsis

```
void w1_pre_write (struct w1_master * dev);
```

Arguments

dev the master device

Description

Pre-write operation, currently only supporting strong pullups. Program the hardware for a strong pullup, if one has been requested and the hardware supports it.

Name

`w1_post_write` — post-write options

Synopsis

```
void w1_post_write (struct w1_master * dev);
```

Arguments

dev the master device

Description

Post-write operation, currently only supporting strong pullups. If a strong pullup was requested, clear it if the hardware supports them, or execute the delay otherwise, in either case clear the request.

Name

`w1_read_bit` — Generates a write-1 cycle and samples the level.

Synopsis

```
u8 w1_read_bit (struct w1_master * dev);
```

Arguments

dev the master device

Description

Only call if `dev->bus_master->touch_bit` is NULL

Name

`w1_triplet` — * Does a triplet - used for searching ROM addresses.

Synopsis

```
u8 w1_triplet (struct w1_master * dev, int bdir);
```

Arguments

dev the master device

bdir the bit to write if both `id_bit` and `comp_bit` are 0

Return bits

bit 0 = `id_bit` bit 1 = `comp_bit` bit 2 = `dir_taken` If both bits 0 & 1 are set, the search should be restarted.

Return

bit fields - see above